

Cyber-Physical System Fundamentals					AR-215
Rota	Duration	Semester	SWS	Credit Points	Workload
annually SS	1 Semester	2nd (Semester)	4 SWS	6	180 h
<b>1</b>	<b>Modul structure</b>				
	<b>Course (Abbreviation)</b>	<b>Type/ SWS</b>	<b>Presence</b>	<b>Self study</b>	<b>Credits</b>
	a) Cyber-Physical System Fundamentals (CPSF)	Lecture/ 4 SWS	60 h	60 h	4
	b) Cyber-Physical System Fundamentals (CPSF)	Lab	60 h		2
<b>2</b>	<b>Language:</b> English				
<b>3</b>	<p><b>Content:</b> The course is based on the presenter's book on the subject and includes the following topics:</p> <ol style="list-style-type: none"> <li>1. Introduction: Definition of terms, scope of the course</li> <li>2. Specification and modeling: models of computation, communication models, finite state machines, data flow, discrete event models, von-Neumann-models, expressiveness of models</li> <li>3. CPS hardware: hardware-in-the-loop, sampling and A/D-conversion, processing, field-programmable gate arrays (FPGAs), communication hardware, D/A-conversion, sampling theorem, output</li> <li>4. Standard software: embedded operating systems, real-time operating systems, priority inversion, middleware</li> <li>5. Evaluation and validation: objective functions, Pareto-optimality, worst-case execution time, energy consumption, reliability, real-time calculus, verification</li> <li>6. Mapping of applications to execution platforms: standard optimization techniques, real-time scheduling, rate monotonic scheduling, earliest deadline first scheduling, hardware/software partitioning, mapping of applications to heterogeneous multiprocessors</li> <li>7. Selected optimizations.</li> </ol> <p><b>Literature:</b></p> <ul style="list-style-type: none"> <li>• Peter Marwedel: Embedded System Design – Cyber Physical System Fundamentals, Springer, 2010</li> <li>• Lego Mindstorm NXT Technical documentation</li> <li>• Technical documentation for the used finite state machine design tool (StateMate or similar)</li> </ul>				
<b>4</b>	<p><b>Goals</b></p> <p>Students successfully finishing the course should be able to</p> <ul style="list-style-type: none"> <li>• Understand how cyber-physical (CPS) hardware interacts with CPS software and use this knowledge to design CPS software,</li> <li>• Select models of computation and programming languages that are appropriate for a given design problem,</li> <li>• Select an appropriate scheduling technique for embedded systems,</li> </ul> <p>Apply hardware/ software codesign techniques in order to optimize the systems which they are supposed to design.</p>				
<b>5</b>	<p><b>Examination Requirements</b></p> <p>The students have to pass both the lab and the finals.</p>				
<b>6</b>	<p><b>Formality of Examination</b></p> <p><input checked="" type="checkbox"/> Module Finals <span style="float: right;"><input type="checkbox"/> Accumulated Grade</span></p>				
<b>7</b>	<p><b>Module Requirements (Prerequisites)</b></p> <p>Basic knowledge in programming as well as finite-state machines.</p>				

8	<b>Allocation to Curriculum:</b> Program: Automation & Robotics, Field of study: <b>Robotics</b> , <b>Process Automation</b> , <b>Cognitive Systems</b> ,
9	<b>Responsibility/ Lecturer</b> <i>Prof. Dr. Peter Marwedel</i> /Prof. Dr. Peter Marwedel