

Multivariable Control					AR-313
Rota	Duration	Semester	SWS	Credit Points	Workload
annually WS	1 Term	3rd (Semester)	2 SWS	3	90 h
1	Modul structure				
	Course (Abbreviation)	Type/ SWS	Presence	Self study	Credits
	a) Multivariable Control (MVC)	Lecture / 1 SWS	15 h	30 h	2
	b) Multivariable Control (MVC)	Tutorial / 1 SWS	15 h	30 h	1
2	Language English				
3	Content <ul style="list-style-type: none"> • Specification of controller design tasks, design using frequency response approximation performance limitations in SISO control loops. • I/O-system description of multivariable systems, poles, zeros, zero directions, stability criteria. • Classical Design Techniques: Decoupling, sequential loop closure, approximate decoupling, multivariable frequency response approximation, robustness. • Control Structure Selection: Static and dynamic controllability analysis, plant directionality, relative gain array, computation of the attainable performance. <p>The course takes place in the first half of the semester.</p> Literature: <ul style="list-style-type: none"> • Skogestad, S.; Postlethwaite, I.: Multivariable Feedback Control. John Wiley & Sons, 1996. 				
4	Goals After this course, the students will be able to design multivariable controllers for chemical and biochemical processes based on input-output descriptions. They are aware of the limitations of controller performance in the scalar and in the multivariable case and of the influence of plant-model mismatch on controller performance. They can apply modern tools to the selection of control structures.				
5	Examination Requirements The final exam will be an oral (20 minutes) or written and computer-based (1.5 hours) exam, depending on the number of participants (form will be announced in the second week of the course). Active participation and collaboration in 75% of computer exercises is mandatory.				
6	Formality of Examination <input checked="" type="checkbox"/> Module Finals <input type="checkbox"/> Accumulated Grade				
7	Module Requirements (Prerequisites) Basic knowledge of dynamic systems and control, as e.g. provided by the course Control Theory and Applications.				
8	Allocation to Curriculum: Program: Automation & Robotics, Field of study: Process Automation, Robotics, Cognitive Systems				
9	Responsibility/ Lecturer <i>Prof. Dr. S. Engell/Prof. Dr. S. Engell</i>				